# NEW APPROACHES TOWARDS A FINITE-ELEMENT BASED HARTREE-FOCK METHOD

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#### INTRODUCTION

Employing a finite-element basis in electronic structure calculations provides an alternative to the commonly used atom-centered (AC) basis functions [1]. Potential benefits:

- Sparse, nearly diagonal-dominant matrices for local operators
- Easy parallelisation of code



- The grid (i.e. the basis) adapts to the molecular structure
- Intrinsic multiscale methods possible
- Reduction of implicit bias imposed by AC basis
- More flexible with respect to boundary conditions and potentials

## HARTREE-FOCK IN THE WEAK FORMULATION

• Consider orbital in FE basis:  $\psi_i = \sum_j z_j^{(i)} \varphi_j$  and define

$$a(f,g) := \int_{\Omega} \frac{1}{2} \nabla f(\underline{r}) \cdot \nabla g(\underline{r}) + f(\underline{r}) \,\hat{\mathcal{V}}(\underline{r}) \,g(\underline{r}) \,\mathrm{d}\underline{r} \tag{1}$$

$$\hat{\mathcal{V}} = \underbrace{\hat{\mathcal{V}}_{0}}_{\text{electron-nuclear interaction}} + \underbrace{\hat{\mathcal{V}}_{H}}_{\text{Hartree potential}} + \underbrace{\hat{\mathcal{V}}_{x}}_{\text{exchange potential}} \tag{2}$$

$$m(f,g) := \int_{\Omega} f(\underline{r}) \cdot g(\underline{r}) \,\mathrm{d}\underline{r} \tag{3}$$

• We solve the Hartree-Fock (HF) equations in its weak form

$$\forall \varphi_j : a(\varphi_j, \psi_i) = \varepsilon_i \, m(\varphi_j, \psi_i)$$
  

$$\Rightarrow \qquad \mathbf{A}\underline{z}^{(i)} = \varepsilon_i \mathbf{M}\underline{z}^{(i)}$$
(4)

where  $A_{jk} = a(\varphi_j, \varphi_k)$  and  $M_{jk} = m(\varphi_j, \varphi_k)$ . • Hartree potential  $\hat{\mathcal{V}}_H$  obtained in linear time by solving Poisson equation



- Use approximate Fock matrix **A** until final grid found
- Autogeneration of grids and grid reuse is possible
- Back end for FE: deal.ii library

### PRACTICAL CHALLENGES OF FINITE-ELEMENT HF

- Good discretisation requires large basis sets (more than 10<sup>6</sup> functions)
- FE theory: Discretisation matrices of local operators are sparse
- But: Hartree-Fock exchange  $\hat{\mathcal{V}}_x$  is non-local
- Split up  $\mathbf{A} = \mathbf{A}_{\text{local}} + \mathbf{V}_x$ , where the exchange matrix is

#### $-\Delta \hat{\mathcal{V}}_H(\underline{\boldsymbol{r}}) = \rho(\underline{\boldsymbol{r}})$

• All operators except  $\hat{\mathcal{V}}_x$  are **local**, i.e. they do not correlate two points in space

# FINITE ELEMENTS (FES)

- Piecewise polynomials  $\{\varphi_i\}$  on discretised grid
- Only non-zero in a few grid cells  $\Rightarrow$  strongly **localised**
- At nodal points  $\{\underline{x}_k\}$ :  $\varphi_j(\underline{x}_k) = \delta_{jk}$



- Affine map between each cell on discretisation grid a reference cell, e.g.  $[0,1]^{\dim}$ .
- FEs can be generated by applying those affine maps to a small number of shape functions (Lagrange polynomials) defined on the reference cell.



$$(V_x)_{jk} = \int_{\Omega} \int_{\Omega} \varphi_j(\underline{\boldsymbol{r}}) \frac{\sum_i \psi_i(\underline{\boldsymbol{r}}) \psi_i(\underline{\boldsymbol{r}}')}{|\underline{\boldsymbol{r}} - \underline{\boldsymbol{r}}'|} \varphi_k(\underline{\boldsymbol{r}}') \, \mathrm{d}\underline{\boldsymbol{r}} \, \mathrm{d}\underline{\boldsymbol{r}}' \tag{6}$$

0.0

-1.5

-3.0

-4.5

-6.0

-7.5

-9.0

-10.5

-12.0



Visualisation of an example for  $\mathbf{V}_x$ colouring depends on the log of the entry values,  $\log |(A_{\text{local}})_{jk}|$  or  $\log |(V_x)_{jk}|$ , respectively

- $\Rightarrow$  Computational cost scales at least quadratically with basis set size
- $\Rightarrow$  Memory cost scales quadratically if full Fock matrix **A** is stored

### OUTLOOK

(5)

• The computation of the exchange matrix-vector product can be written as

2D quadratic shape functions

- Noteworthy properties [2]:
  - A posteriori error estimation: Estimate cell-wise error bound for the solution orbitals
  - Adaptive grid refinement: User defined metric determines which cells are refined on the next finer grid level
  - $\Rightarrow$  Grid can adopt to molecule by minimising *a posteriori* error

 $(\mathbf{V}_x \underline{\boldsymbol{z}}^{(l)})_j = \int_{\Omega} \varphi_j(\underline{\boldsymbol{r}}) \sum_i \tilde{V}_{il}(\underline{\boldsymbol{r}}) \psi_i(\underline{\boldsymbol{r}}) \,\mathrm{d}\underline{\boldsymbol{r}}$  $-\Delta \tilde{V}_{il}(\boldsymbol{r}) = \psi_i(\boldsymbol{r})\psi_l(\boldsymbol{r})$ 

- Each application of **A** requires only  $N_{\text{orbitals}}^2$  Poisson equations to be solved  $\Rightarrow$  Linear scaling in memory and computational cost
- Use multigrid methods to reduce the number of diagonalisation iterations [4]
- Test non-linear diagonalisation schemes
- Develop a good approximation for the Fock operator in the FE context

## REFERENCES

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